Feynman integrals associated to elliptic curves

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- Part I: No elliptic curves
- Part II: One elliptic curve
- Part III: Several elliptic curves

Part I

No elliptic curves

(Introduction to Feynman integrals)

Experiments in high-energy physics



Scattering amplitudes

For a theoretical description we need to know the scattering amplitude:



 N_{ext} external particles with momenta $p_1, ..., p_{N_{\text{ext}}}$.

Momentum conservation: $p_1 + \ldots + p_{N_{\text{ext}}} = 0$.

Feynman diagrams

We may compute the scattering amplitude within perturbation theory:



Feynman integrals

Associate to a Feynman graph *G* with N_{ext} external lines, *n* internal lines and *l* loops the set of Feynman integrals

$$I_{\mathbf{v}_{1}\mathbf{v}_{2}...\mathbf{v}_{n}} = \int \frac{d^{D}k_{1}}{(2\pi)^{D}} ... \frac{d^{D}k_{l}}{(2\pi)^{D}} \prod_{j=1}^{n} \frac{1}{(q_{j}^{2} - m_{j}^{2})^{\mathbf{v}_{j}}},$$

with $v_j \in \mathbb{Z}$ and $v = v_1 + \ldots + v_n$.

Pinching of propagators

If for some exponent we have $v_j = 0$, the corresponding propagator is absent and the topology simplifies:



Within dimensional regularisation we have for any loop momentum k_i and $v \in \{p_1,...,p_{N_{\mathrm{ext}}},k_1,...,k_l\}$

$$\int \frac{d^D k_1}{(2\pi)^D} \dots \frac{d^D k_l}{(2\pi)^D} \frac{\partial}{\partial k_i^{\mu}} v^{\mu} \prod_{j=1}^n \frac{1}{\left(q_j^2 - m_j^2\right)^{\nu_j}} = 0.$$

Working out the derivatives leads to relations among integrals with different sets of indices $(v_1, ..., v_n)$.

This allows us to express most of the integrals in terms of a few master integrals.

Tkachov '81, Chetyrkin '81

Expressing all integrals in terms of the master integrals requires to solve a rather large linear system of equations.

This system has a block-triangular structure, originating from subtopologies.

Order the integrals by complexity (more propagators \Rightarrow more difficult)

Solve the system bottom-up, re-using the results for the already solved sectors.

Let x_k be a kinematic variable. Let $I_i \in \{I_1, ..., I_{N_{master}}\}$ be a master integral. Carrying out the derivative

 $\frac{\partial}{\partial x_k} I_i$

under the integral sign and using integration-by-parts identities allows us to express the derivative as a linear combination of the master integrals.

$$\frac{\partial}{\partial x_k} I_i = \sum_{j=1}^{N_{\text{master}}} a_{ij} I_j$$

(Kotikov '90, Remiddi '97, Gehrmann and Remiddi '99)

Differential equations

Let us formalise this:

 $\vec{I} = (I_1, ..., I_{N_{\text{master}}}),$ set of master integrals, $\vec{x} = (x_1, ..., x_{N_B}),$ set of kinematic variables the master integrals depend on.

We obtain a system of differential equations of Fuchsian type

$$d\vec{I} + A\vec{I} = 0,$$

where A is a matrix-valued one-form

$$A = \sum_{i=1}^{N_B} A_i dx_i.$$

The matrix-valued one-form A satisfies the integrability condition

 $dA + A \wedge A = 0$ (flat Gauß-Manin connection).

Computation of Feynman integrals reduced to solving differential equations!

The ϵ -form of the differential equation

If we change the basis of the master integrals $\vec{J} = U\vec{I}$, the differential equation becomes

$$(d+A')\vec{J}=0, \qquad A'=UAU^{-1}+UdU^{-1}$$

Suppose one finds a transformation matrix U, such that

$$A' = \epsilon \sum_{j} C_{j} d \ln p_{j}(\vec{x}),$$

where

- ε appears only as prefactor,
- C_i are matrices with constant entries,
- $p_j(\vec{x})$ are polynomials in the external variables,

then the system of differential equations is easily solved in terms of multiple polylogarithms.

Henn '13

Transformation to the ϵ -form

We may

• change the basis of the master integrals

$$\vec{I} \rightarrow U\vec{I},$$

where U is rational in the kinematic variables

Henn '13; Gehrmann, von Manteuffel, Tancredi, Weihs '14; Argeri et al. '14; Lee '14; Meyer '16; Prausa '17; Gituliar, Magerya '17; Lee, Pomeransky '17;

• perform a rational / algebraic transformation on the kinematic variables

$$(x_1,\ldots,x_{N_B}) \quad \rightarrow \quad (x'_1,\ldots,x'_{N_B}),$$

often done to absorb square roots.

Becchetti, Bonciani, '17, Besier, van Straten, S.W., '18

Multiple polylogarithms

Definition based on nested sums:

$$\mathsf{Li}_{m_1,m_2,\dots,m_k}(x_1,x_2,\dots,x_k) = \sum_{n_1 > n_2 > \dots > n_k > 0}^{\infty} \frac{x_1^{n_1}}{n_1^{m_1}} \cdot \frac{x_2^{n_2}}{n_2^{m_2}} \cdot \dots \cdot \frac{x_k^{n_k}}{n_k^{m_k}}$$

Definition based on iterated integrals:

$$G(z_1,...,z_k;y) = \int_0^y \frac{dt_1}{t_1-z_1} \int_0^{t_1} \frac{dt_2}{t_2-z_2} \dots \int_0^{t_{k-1}} \frac{dt_k}{t_k-z_k}$$

Conversion:

$$\mathsf{Li}_{m_1,...,m_k}(x_1,...,x_k) = (-1)^k G_{m_1,...,m_k}\left(\frac{1}{x_1},\frac{1}{x_1x_2},...,\frac{1}{x_1...x_k};1\right)$$

Short hand notation:

$$G_{m_1,...,m_k}(z_1,...,z_k;y) = G(\underbrace{0,...,0}_{m_1-1},z_1,...,z_{k-1},\underbrace{0,...,0}_{m_k-1},z_k;y)$$

Example

Let us consider a simple example: One integral *I* in one variable *x* with boundary condition I(0) = 1. Consider the differential equation

$$(d+A)I = 0, \qquad A = -\varepsilon d\ln(x-1).$$

Note that

$$d\ln(x-1) = \frac{dx}{x-1}$$

and

$$I(x) = 1 + \varepsilon G(1;x) + \varepsilon^2 G(1,1;x) + \varepsilon^3 G(1,1,1;x) + \dots$$

Iterated integrals

For $\omega_1, ..., \omega_k$ differential 1-forms on a manifold M and $\gamma : [0,1] \to M$ a path, write for the pull-back of ω_j to the interval [0,1]

$$f_j(\lambda) d\lambda = \gamma^* \omega_j.$$

The iterated integral is defined by (Chen '77)

$$I_{\gamma}(\boldsymbol{\omega}_{1},...,\boldsymbol{\omega}_{k};\boldsymbol{\lambda}) = \int_{0}^{\boldsymbol{\lambda}} d\boldsymbol{\lambda}_{1}f_{1}(\boldsymbol{\lambda}_{1})\int_{0}^{\boldsymbol{\lambda}_{1}} d\boldsymbol{\lambda}_{2}f_{2}(\boldsymbol{\lambda}_{2})...\int_{0}^{\boldsymbol{\lambda}_{k-1}} d\boldsymbol{\lambda}_{k}f_{k}(\boldsymbol{\lambda}_{k}).$$

Iterated integrals

Example 1: Multiple polylogarithms (Goncharov '98)

$$\omega_j = \frac{d\lambda}{\lambda-z_j}.$$

Example 2: Iterated integrals of modular forms (Brown '14): $f_j(\tau)$ a modular form,

$$\omega_j = 2\pi i f_j(\tau) d\tau.$$

Example 3: Iterated integrals on a covering space of a fixed single elliptic curve, also known as "elliptic polylogarithms" (Broedel, Duhr, Dulat, Penante, Tancredi, '17-'19).

Part II

One elliptic curve

(Feynman integrals beyond multiple polylogarithms)

Single-scale Feynman integrals beyond multiple polylogarithms

Not all Feynman integrals are expressible in terms of multiple polylogarithms!



The Picard-Fuchs operator

Let *I* be one of the master integrals $\{I_1, ..., I_{N_{master}}\}$. Choose a path $\gamma : [0, 1] \to M$ and study the integral *I* as a function of the path parameter λ .

Instead of a system of N_{master} first-order differential equations

 $(d+A)\vec{I} = 0,$

we may equivalently study a single differential equation of order N_{master}

$$\sum_{j=0}^{N_{ ext{master}}} p_j(\lambda) rac{d^j}{d\lambda^j} I \quad = \quad 0.$$

We may work modulo sub-topologies and ϵ -corrections:

$$L = \sum_{j=0}^{r} p_j(\lambda) \frac{d^j}{d\lambda^j}$$
: $LI = 0 \mod (\text{sub-topologies}, \epsilon\text{-corrections})$

Suppose the differential operator factorises into linear factors:

$$L = \left(a_r(\lambda)\frac{d}{d\lambda} + b_r(\lambda)\right) \dots \left(a_2(\lambda)\frac{d}{d\lambda} + b_2(\lambda)\right) \left(a_1(\lambda)\frac{d}{d\lambda} + b_1(\lambda)\right)$$

Iterated first-order differential equation.

Denote homogeneous solution of the j-th factor by

$$\Psi_j(\lambda) = \exp\left(-\int_0^\lambda d\kappa \, \frac{b_j(\kappa)}{a_j(\kappa)}\right).$$

Full solution given by iterated integrals

$$C_1\psi_1(\lambda) + C_2\psi_1(\lambda)\int_0^\lambda d\lambda_1 \frac{\psi_2(\lambda_1)}{a_1(\lambda_1)\psi_1(\lambda_1)} + C_3\psi_1(\lambda)\int_0^\lambda d\lambda_1 \frac{\psi_2(\lambda_1)}{a_1(\lambda_1)\psi_1(\lambda_1)}\int_0^{\lambda_1} d\lambda_2 \frac{\psi_3(\lambda_2)}{a_2(\lambda_2)\psi_2(\lambda_2)} + \dots$$

Multiple polylogarithms are of this form.

Suppose the differential operator

$$\sum_{j=0}^r p_j(\lambda) \frac{d^j}{d\lambda^j}$$

does not factor into linear factors.

The next more complicate case:

The differential operator contains one irreducible second-order differential operator

$$a_j(\lambda) \frac{d^2}{d\lambda^2} + b_j(\lambda) \frac{d}{d\lambda} + c_j(\lambda)$$

The differential operator of the second-order differential equation

$$\left[k\left(1-k^{2}\right)\frac{d^{2}}{dk^{2}}+\left(1-3k^{2}\right)\frac{d}{dk}-k\right]f(k) = 0$$

is irreducible.

The solutions of the differential equation are K(k) and $K(\sqrt{1-k^2})$, where K(k) is the complete elliptic integral of the first kind:

$$K(k) = \int_{0}^{1} \frac{dx}{\sqrt{(1-x^2)(1-k^2x^2)}}.$$

An example from physics: The two-loop sunrise integral

$$S_{\mathbf{v}_1\mathbf{v}_2\mathbf{v}_3}(D,x) = \underbrace{\begin{array}{c}1\\2\\3\end{array}}$$

Picard-Fuchs operator for $S_{111}(2,x)$:

$$L = x(x-1)(x-9)\frac{d^2}{dx^2} + (3x^2 - 20x + 9)\frac{d}{dx} + (x-3)$$

(Broadhurst, Fleischer, Tarasov '93)

Irreducible second-order differential operator.

Picard-Fuchs operator for the periods of a family of elliptic curves.

The elliptic curve

How to get the elliptic curve?

• From the Feynman graph polynomial:

$$-x_1x_2x_3x + (x_1 + x_2 + x_3)(x_1x_2 + x_2x_3 + x_3x_1) = 0$$

• From the maximal cut:

$$v^{2} - (u - x)(u - x + 4)(u^{2} + 2u + 1 - 4x) = 0$$

Baikov '96; Lee '10; Kosower, Larsen, '11; Caron-Huot, Larsen, '12; Frellesvig, Papadopoulos, '17; Bosma, Sogaard, Zhang, '17; Harley, Moriello, Schabinger, '17

The periods ψ_1 , ψ_2 of the elliptic curve are solutions of the homogeneous differential equation.

Adams, Bogner, S.W., '13; Primo, Tancredi, '16

Variables

Recall

$$x = \frac{p^2}{m^2}.$$

Set

$$au=rac{{f \psi}_2}{{f \psi}_1}, \qquad q\,=\,e^{2i\pi au}.$$

Change variable from x to τ (or q) (Bloch, Vanhove, '13).

Bases of lattices

The periods ψ_1 and ψ_2 generate a lattice. Any other basis as good as (ψ_2, ψ_1) . Convention: Normalise $(\psi_2, \psi_1) \rightarrow (\tau, 1)$ where $\tau = \psi_2/\psi_1$.



It is not possible to obtain an ϵ -form by a rational/algebraic change of variables and/or a rational/algebraic transformation of the basis of master integrals.

However by factoring off the (non-algebraic) expression ψ_1/π from the master integrals in the sunrise sector one obtains an ϵ -form:

$$I_1 = 4\varepsilon^2 S_{110} \left(2 - 2\varepsilon, x \right), \quad I_2 = -\varepsilon^2 \frac{\pi}{\psi_1} S_{111} \left(2 - 2\varepsilon, x \right), \quad I_3 = \frac{1}{\varepsilon} \frac{1}{2\pi i} \frac{d}{d\tau} I_2 + \frac{1}{24} \left(3x^2 - 10x - 9 \right) \frac{\psi_1^2}{\pi^2} I_2.$$

If in addition one makes a (non-algebraic) change of variables from x to τ , one obtains

$$\frac{d}{d\tau}\vec{I} = \epsilon A(\tau) \vec{I},$$

where $A(\tau)$ is an ε -independent 3 \times 3-matrix whose entries are modular forms.

The matrix $A(\tau)$ is given by

$$A(au) = egin{pmatrix} 0 & 0 & 0 \ 0 & -f_2(au) & 1 \ rac{1}{4}f_3(au) & f_4(au) & -f_2(au) \end{pmatrix},$$

where f_2 , f_3 and f_4 are modular forms of $\Gamma_1(6)$ of modular weight 2, 3 and 4, respectively.

 I_1 , I_2 and I_3 are expressed as iterated integrals of modular forms to all orders in ε .

Adams, S.W., '17, '18

Feynman integrals evaluating to iterated integrals of modular forms

This applies to a wider class of Feynman integrals:



Part III

Several elliptic curves

(An example from top-pair production)

Kinematics

$$I_{\mathbf{v}_{1}\mathbf{v}_{2}\mathbf{v}_{3}\mathbf{v}_{4}\mathbf{v}_{5}\mathbf{v}_{6}\mathbf{v}_{7}}\left(D,\frac{s}{m^{2}},\frac{t}{m^{2}}\right) = \left(m^{2}\right)^{\sum\limits_{j=1}^{7} \mathbf{v}_{j}-D} \int \frac{d^{D}k_{1}}{\left(2\pi\right)^{D}} \frac{d^{D}k_{2}}{\left(2\pi\right)^{D}} \prod_{j=1}^{7} \frac{1}{P_{j}^{\mathbf{v}_{j}}},$$



$$p_1^2 = p_2^2 = 0,$$
 $p_3^2 = p_4^2 = m^2,$
 $s = (p_1 + p_2)^2,$ $t = (p_2 + p_3)^2.$

Picard-Fuchs operator of elliptic curves

- Sunrise integral: An elliptic curve can be obtained either from
 - Feynman graph polynomial
 - maximal cut

The periods ψ_1 , ψ_2 are the solutions of the homogeneous differential equations.

Adams, Bogner, S.W., '13, '14

• In general: The maximal cuts are solutions of the homogeneous differential equations.

Primo, Tancredi, '16

Search for Feynman integrals, whose maximal cuts are periods of an elliptic curve.

Maximal cuts

Maximal cut: For a Feynman integral

$$I_{\nu_{1}\nu_{2}...\nu_{n}} = (\mu^{2})^{\nu-lD/2} \int \frac{d^{D}k_{1}}{(2\pi)^{D}} ... \frac{d^{D}k_{l}}{(2\pi)^{D}} \prod_{j=1}^{n} \frac{1}{P_{j}^{\nu_{j}}}$$

take the *n*-fold residue at

$$P_1 = \ldots = P_n = 0$$

of the integrand and integrate over the remaining (lD-n) variables along a contour C.

Maximal cuts

Sunrise :

$$\begin{aligned} \operatorname{MaxCut}_{\mathcal{C}} I_{1001001} \left(2 - 2\varepsilon \right) &= \\ \frac{um^2}{\pi^2} \int_{\mathcal{C}} \frac{dP}{\left(P - t \right)^{\frac{1}{2}} \left(P - t + 4m^2 \right)^{\frac{1}{2}} \left(P^2 + 2m^2P - 4m^2t + m^4 \right)^{\frac{1}{2}}} + O(\varepsilon) \,. \end{aligned}$$

Double box :

$$\begin{aligned} \operatorname{MaxCut}_{\mathcal{C}} I_{1111111} \left(4 - 2\varepsilon \right) &= \\ \frac{um^{6}}{4\pi^{4}s^{2}} \int_{\mathcal{C}} \frac{dP}{\left(P - t \right)^{\frac{1}{2}} \left(P - t + 4m^{2} \right)^{\frac{1}{2}} \left(P^{2} + 2m^{2}P - 4m^{2}t + m^{4} - \frac{4m^{2} \left(m^{2} - t \right)^{2}}{s} \right)^{\frac{1}{2}} + O\left(\varepsilon\right). \end{aligned}$$

Three elliptic curves

$$E^{(a)} : w^{2} = (z-t) (z-t+4m^{2}) (z^{2}+2m^{2}z-4m^{2}t+m^{4})$$

$$(z^{2}+2m^{2}z-4m^{2}t+m^{4}-\frac{4m^{2} (m^{2}-t)^{2}}{s})$$

$$E^{(b)} : w^{2} = (z-t) (z-t+4m^{2}) (z^{2}+2m^{2}z-4m^{2}t+m^{4}-\frac{4m^{2} (m^{2}-t)^{2}}{s})$$

$$E^{(c)} : w^{2} = (z-t) (z-t+4m^{2}) (z^{2}+\frac{2m^{2} (s+4t)}{(s-4m^{2})}z+\frac{sm^{2} (m^{2}-4t)-4m^{2}t^{2}}{s-4m^{2}})$$

Remarks

- $E^{(a)}$ gives rise to iterated integrals of modular forms of $\Gamma_1(6)$.
- For $s \to \infty$ the curves $E^{(b)}$ and $E^{(c)}$ degenerate to $E^{(a)}$.
- If we would have only one curve, we expect that the result can be written in elliptic polylogarithms.
- We have three elliptic curves.

Results

The differential equation for the master integrals can be brought into the form

$$d\vec{I} = \epsilon A\vec{I},$$

where A is independent of ε .

The Laurent expansion in ε of all master integrals can be computed systematically to all orders in ε in terms of iterated integrals.

The solution

- reduces to multiple polylogarithms for $t = m^2$ and
- reduces to iterated integrals of modular forms of $\Gamma_1(6)$ for $s = \infty$.

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Adams, Chaubey, S.W., '18
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Conclusions

- Loop integrals with masses important for top, W/Z- and H-physics.
- May involve elliptic sectors from two loops onwards.
- There is a class of Feynman integrals evaluating to iterated integrals of modular forms.
- The planar double box integral relavant to $t\bar{t}$ -production with a closed top loop depends on two variables and involves several elliptic sub-sectors. More than one elliptic curve occurs. Results expressed in terms of Chen's iterated integrals.
- We may expect more results in the near future.